

Today: Discrete Time Systems.

Let's start w/ an example:

Ex: Fibonacci sequence.

0 1 1 2 3 5 8 13 21 ...

Write this as a difference equation:

$$y[n] = y[n-1] + y[n-2].$$

w/ initial conditions

$$y[0] = 0.$$

$$y[1] = 1.$$

Before drawing block diagram, can we think of it as ^{the response of} a system w/ zero initial cond?

$$y[n] = y[n-1] + y[n-2] + x[n].$$

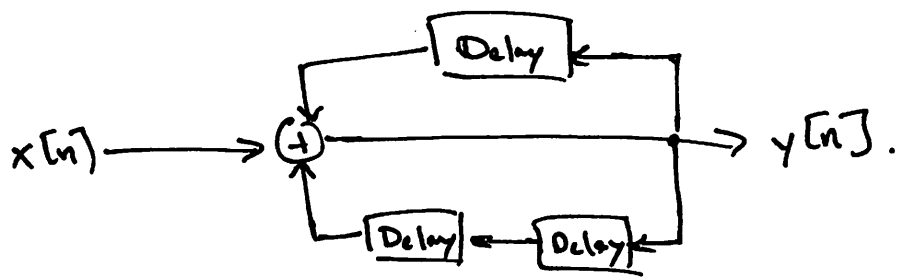
~~$$y[n] = y[n-1] + y[n-2]$$~~

$$y[n] = 0 \quad n < 0.$$

$$x[n] = ?$$

$$x[n] = \delta[n-1].$$

Now draw the block diagram.



Now write it as a polynomial.

$$y[n] \Rightarrow Y.$$

$$y[n-1] \Rightarrow RY.$$

$$y[n-2] \Rightarrow R^2 Y.$$

$$Y = RY + R^2 Y + X.$$

$$(1 - R - R^2) Y = X.$$

$$\frac{Y}{X} = \frac{1}{(1 - R - R^2)}. \quad \leftarrow \text{gives unit sample response.}$$

Can we expand that out?

$$\begin{array}{r}
 1 - R - R^2 \overline{) 1} \\
 \underline{1 - R - R^2} \\
 R + R^2 \\
 \underline{R - R^2 - R^3} \\
 2R^2 + R^3 \\
 \underline{2R^2 - 2R^3 - 2R^4} \\
 3R^3 + 2R^4 \\
 \underline{3R^3 - 3R^4 - 3R^5} \\
 5R^4 + 3R^5 + \dots
 \end{array}$$

↑
Is this the
Fibonacci seq?
(No! shifted by 1)
as expected.

Aside: Polynomial division.

$$\text{Ex } \frac{3x^3 - 2x^2 + 4x - 3}{x^2 + 3x + 3}$$

particularly useful
when $\text{deg denom} \leq \text{deg num}$.

Long-division

$$\begin{array}{r} 3x - 11 \\ x^2 + 3x + 3 \overline{) 3x^3 - 2x^2 + 4x - 3} \\ \underline{3x^3 + 9x^2 + 9x} \\ -11x^2 - 5x - 3 \\ \underline{-11x^2 - 33x - 33} \\ 28x + 30 \end{array}$$

← after stop here.

$$\Rightarrow \frac{3x^3 - 2x^2 + 4x - 3}{x^2 + 3x + 3} = 3x - 11 + \frac{28x + 30}{x^2 + 3x + 3}$$

You try:

$$\frac{x^3 - 3x^2 + 5x - 3}{x - 1}$$

$$\text{Answer: } = x^2 - 2x + 3$$

Feedback.

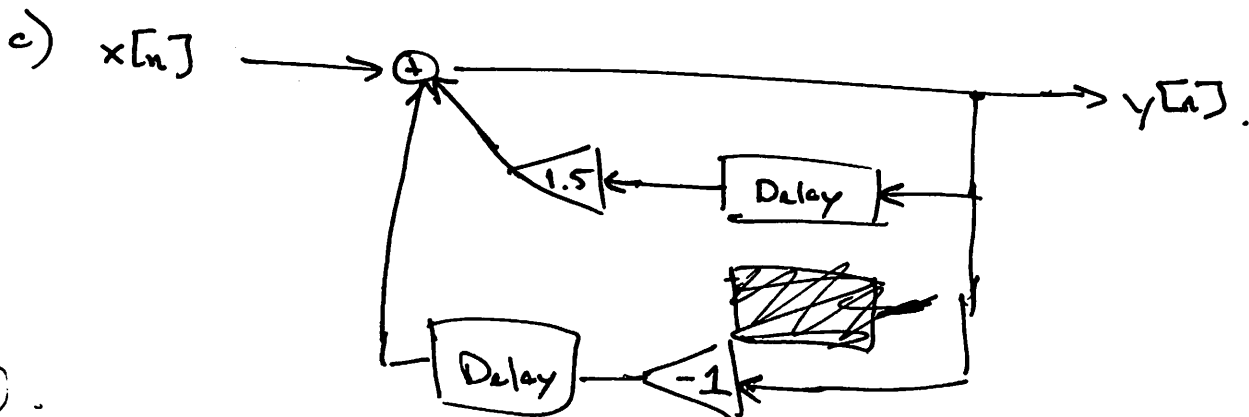
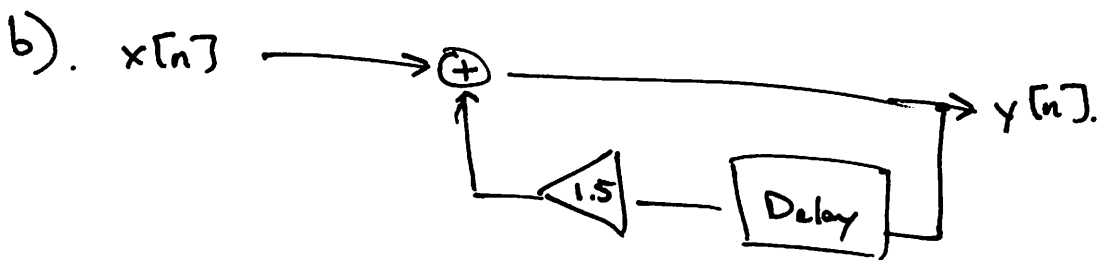
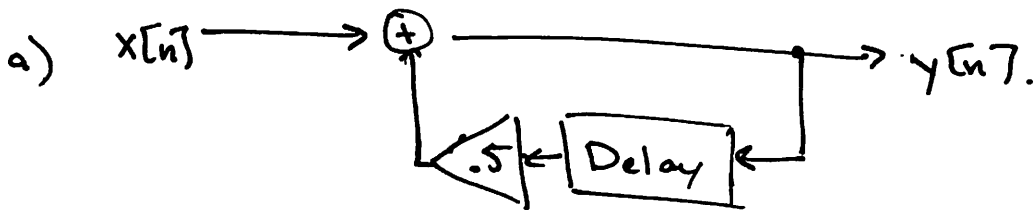
Absolutely essential concept for control design.

Fibonacci example had feedback.

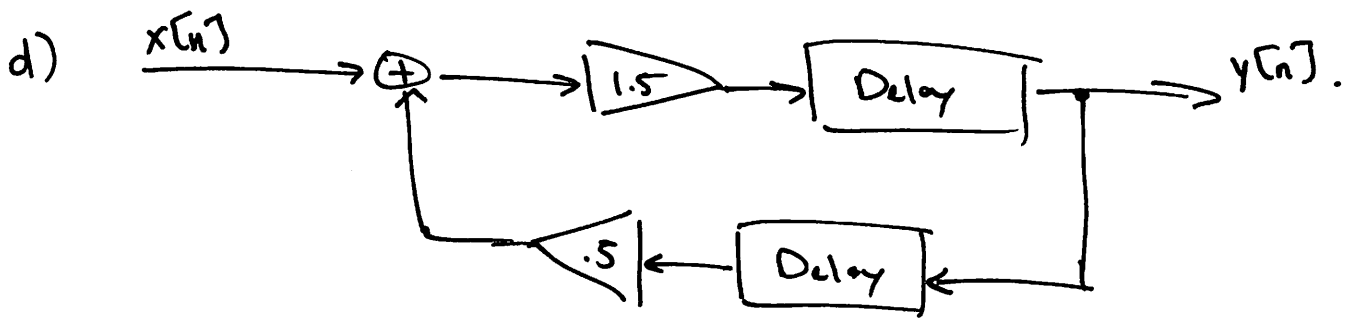
it lead to an exponential growth. ~~from~~ a^n unit sample response.

~~Feedback~~ Feedback often, but not always

Q: ~~How~~ Which of the following systems have divergent unit sample responses? (starting from rest).



④



A: a) No.

$$y[0] = 1.$$

$$y[1] = .5$$

$$.25$$

$$.125.$$

Can always

do it by

stepping

through time.

b) Yes.

$$y[0] = 1$$

$$y[1] = 1.5$$

$$= \frac{9}{4} = 2.25.$$

$$= :$$

Could also have seen it by writing polynomial.

$$a) Y = X + .5RY.$$

$$\frac{Y}{X} = \frac{1}{1-.5R}.$$

$$\frac{1}{1-p.R} = 1 + pR + p^2R^2 + p^3R^3 + \dots$$

will converge if $|p| < 1$

p is called
a "pole"

$$b) \frac{Y}{X} = \frac{1}{1-1.5R} \text{ diverge.}$$

e) Won't diverge:

It's equivalent to system 0!

* One interpretation
We stabilized
an unstable
system.

$$Y = X + 1.5RY - 1RY = X + .5RY.$$

d) ← won't diverge (check by stepping through)
 $Y = 1.5R(X + .5RY).$

$$(1 - \frac{3}{4}R^2) Y = \frac{3}{2}RX.$$

can factor this into.

$$(1 - \frac{\sqrt{3}}{2}R)(1 + \frac{\sqrt{3}}{2}R) Y = 1.5RX.$$

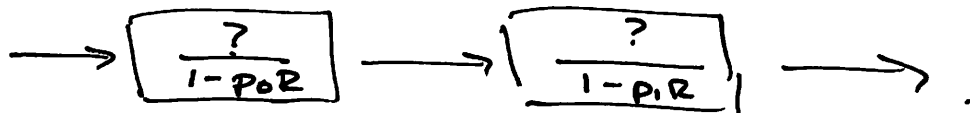
↑ $|p_0| < 1$ ↑ $|p_1| < 1$.

we'll see in lecture tomorrow

that this can be written

as a cascade of two systems

w/ ~~p_0~~ poles p_0 and p_1 .



Very powerful idea.