Final Examination in Linear Algebra: 18.06

May 18, 1999 1:30 – 4:30 Professor Strang

Your name is:										
Secret Code (optional):									Grading	$\frac{1}{2}$
Please circle your recitation:										$\frac{2}{3}$
1) 2)	Mon Mon	2-3 3-4	2-131 2-131	S. Kleiman S. Hollander	$5) \\ 6) \\ -$	Tues Tues	12-1 1-2	2-131 2-131	S. Kleiman S. Kleiman	$5\\6\\7$
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Answer all 9 questions on these pages. This is a closed book exam. Calculators are not needed in any way and therefore not allowed (to be fair to all). *Grades are known only to your recitation instructor* (who is free to post with secret codes and to return exams in person). Solutions will be posted on the web in a few days. Best wishes for the summer and thank you for taking 18.06.

GS

1 Suppose the matrix A is the product

$$A = \left[\begin{array}{rrrr} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 5 & 4 & 3 \end{array} \right] \left[\begin{array}{rrrr} 1 & 0 & 3 & 4 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \,.$$

- (a) (3 points) Give a basis for the nullspace of A.
- (b) (3 points) Give a basis for the row space of A.
- (c) (2 points) Express row 3 of A as a combination of your basis vectors in your answer to (b).
- (d) (3 points) What is the dimension of the nullspace of A^T ?

- **2** Suppose A is a 5 by 7 matrix, and Ax = b has a solution for every right side b.
 - (a) (3 points) What do we know about the column space of A?
 - (b) (3 points) What do we know about the rows of A?
 - (c) (3 points) What do we know about the nullspace of A?
 - (d) (3 points) True or false (with reason):

The columns of A are a basis for the column space of A.

Your answers could refer to dimension/basis/linear independence/spanning a space.

- **3** Assume that A is invertible and permutations are not needed in elimination if possible.
 - (a) (2 points) Are the pivots of A^{-1} equal to $\frac{1}{\text{pivots of }A}$? If yes, give a reason; if no, give an example.
 - (b) (3 points) Is the product of pivots of A^{-1} equal to $\frac{1}{\text{product of pivots of }A}$? If yes, give a reason; if no, give an example.
 - (c) (3 points) Apply block elimination to the 2n by 2n matrix

$$M = \left[\begin{array}{cc} A & I \\ -I & 0 \end{array} \right]$$

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Multiply block row 1 by a suitable matrix and add to block row 2. What matrix appears in the (2, 2) block?

(d) (3 points) What is the determinant of M? Explain the final plus or minus sign.

4 Suppose A has eigenvalues $\lambda_1 = 3, \ \lambda_2 = 1, \ \lambda_3 = 0$ with corresponding eigenvectors

$$x_1 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}, \quad x_2 = \begin{bmatrix} 0\\1\\1 \end{bmatrix}, \quad x_3 = \begin{bmatrix} 0\\0\\1 \end{bmatrix}$$

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(a) (3 points) How do you know that the third column of A contains all zeros?

- (b) (3 points) Find the matrix A.
- (c) (3 points) By transposing $S^{-1}AS = \wedge$, find the eigenvectors y_1, y_2, y_3 of A^T . (I am looking for specific vectors like x_1, x_2, x_3 above.)

5 This problem computes the plane z = Cx + Dy + E that is closest (in the least squares sense) to these four measurements:

At x = 1, y = 0 measurement gives z = 1At x = 1, y = 2 measurement gives z = 3At x = 0, y = 1 measurement gives z = 5At x = 0, y = 2 measurement gives z = 0

- (a) (3 points) Write down the linear system Ax = b with unknown vector x = (C, D, E)that would give a plane going exactly through the four given points — except that this particular system has no solution.
- (b) (3 points) Show that this system Ax = b has no solution!
- (c) (3 points) Find the best least squares solution $\hat{x} = (\hat{C}, \hat{D}, \hat{E})$.
- (d) (3 points) The error vector $e = (e_1, e_2, e_3, e_4)$ in the underlying projection problem is perpendicular to which vectors? You don't have to compute e but you do have to say which specific numerical vectors it is perpendicular to.

- 6 (a) (3 points) The vectors $q_1 = \frac{1}{\sqrt{50}} \begin{bmatrix} 3\\ 4\\ 5 \end{bmatrix}$ and $q_2 = \frac{1}{5} \begin{bmatrix} 4\\ -3\\ 0 \end{bmatrix}$ are orthonormal. Find one more vector to complete an orthonormal basis for \mathbf{R}^3 .
 - (b) (3 points) In solving part (a), you might start with a vector like $a_3 = (0, 0, 1)$ and find q_3 . Which vectors a_3 would not work as starting vectors to find q_3 by Gram-Schmidt? How many different real vectors q_3 will give a correct answer to part (a)?
 - (c) (3 points) Project the vector $a_3 = (0, 0, 1)$ onto the plane spanned by q_1 and q_2 . Find its projection p.

- 7 In each part, find the required matrix or explain why such a matrix does not exist.
 - (a) (3 points) The matrices A and A^T and $A + A^T$ have ranks 2 and 1 and 3.
 - (b) (3 points) The solution to Ax = 0 is unique, but the solution to $A^Tx = 0$ is not unique.
 - (c) (3 points) The powers A^k do not approach the zero matrix as $k \to \infty$, but the exponential e^{At} does approach the zero matrix as $t \to \infty$.
 - (d) (3 points) The complete solution to

$$Ax = \begin{bmatrix} 1\\1\\2 \end{bmatrix} \quad \text{is} \quad x = \begin{bmatrix} 1\\1\\1 \end{bmatrix} + c_1 \begin{bmatrix} 1\\0\\1 \end{bmatrix} + c_2 \begin{bmatrix} -1\\1\\0 \end{bmatrix}$$

(e) (3 points) The pivots are -1 and -2 but the eigenvalues are +1 and +2.
(Symmetric matrix not required, row exchanges not required.)

- 8 (a) (3 points) The "big formula" for a 6 by 6 determinant has 6! = 720 terms. How many of those terms are sure to be zero if we know that $a_{15} = 0$?
 - (b) (2 points) If U and V are 3 by 3 orthogonal matrices, is their product UV always orthogonal? Why (give reason) or why not (give example)?
 - (c) (2 points) If A and B are 3 by 3 symmetric matrices, is their product AB always symmetric? Why (give reason) or why not (give example)?
 - (d) (3 points) For which numbers c is the matrix A positive definite? For which numbers c is A^2 positive definite? Why?

$$A = \left[\begin{array}{rrrr} 1 & 2 & 3 \\ 2 & c & 4 \\ 3 & 4 & 9 \end{array} \right]$$

9 Suppose the 3 by 3 matrix A has the following property Z: Along each of its rows, the entries add up to zero.

- (a) (3 points) Find a nonzero vector in the nullspace of A.
- (b) (3 points) Prove that A^2 also has property Z.
- (c) (3 points) What can you say about the dimension of the nullspace of A^T and why?
- (d) (2 points) Find an eigenvalue of the matrix A + 4I.