18.06	Professor	Stran



## Please circle your recitation:

1)	M 2	2-131	A. Ritter	2-085	2-1192	afr
2)	M 2	4-149	A. Tievsky	2-492	3-4093	tievsky
3)	М 3	2-131	A. Ritter	2-085	2-1192	afr
4)	M 3	2-132	A. Tievsky	2-492	3-4093	tievsky
5)	T 11	2-132	J. Yin	2-333	3-7826	jbyin
6)	T 11	8-205	A. Pires	2-251	3-7566	arita
7)	T 12	2-132	J. Yin	2-333	3-7826	jbyin
8)	T 12	8-205	A. Pires	2-251	3-7566	arita
9)	T 12	26-142	P. Buchak	2-093	3-1198	pmb
10)	Τ1	2-132	B. Lehmann	2-089	3-1195	lehmann
11)	Τ1	26-142	P. Buchak	2-093	3-1198	pmb
12)	Τ1	26-168	P. McNamara	2-314	4-1459	petermc
13)	T $2$	2-132	B. Lehmann	2-089	2-1195	lehmann
14)	T $2$	26-168	P. McNamara	2-314	4-1459	petermc

1 (40 pts.) The (real) matrix A is

$$A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & x & 3 \\ 2 & 3 & 6 \end{bmatrix}.$$

- (a) What can you tell me about the eigenvectors of A? What is the sum of its eigenvalues?
- (b) For which values of x is this matrix A positive definite?
- (c) For which values of x is  $A^2$  positive definite? Why?
- (d) If R is any **rectangular** matrix, *prove* from  $x^{\mathrm{T}}(R^{\mathrm{T}}R)x$  that  $R^{\mathrm{T}}R$  is positive semidefinite (or definite). What condition on R is the test for  $R^{\mathrm{T}}R$  to be positive definite?

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2 (30 pts.) The cosine of a matrix is defined by copying the series for  $\cos x$  (which always converges):

$$\cos A = I - \frac{1}{2!}A^2 + \frac{1}{4!}A^4 - \cdots$$

- (a) Suppose  $Ax = \lambda x$ . Show that x is an eigenvector of  $\cos A$ . Find the eigenvalue.
- (b) Find the eigenvalues of  $A = \frac{\pi}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$ . The eigenvectors are (1, 1) and (1, -1). From the eigenvalues and eigenvectors of  $\cos A$ , find that matrix  $\cos A$ .
- (c) The second derivative of the series for  $\cos(At)$  is  $-A^2\cos(At)$ . So  $u(t) = \cos(At)u(0)$  is a short formula for the solution of

$$\frac{d^2u}{dt^2} = -A^2u \text{ starting from } u(0) \text{ with } u'(0) = 0.$$

Now construct that  $u(t) = \cos(At)u(0)$  by the usual three steps when A is diagonalizable:  $Ax_1 = \lambda_1 x_1$ ,  $Ax_2 = \lambda_2 x_2$ ,  $Ax_3 = \lambda_3 x_3$ .

- 1. Expand  $u(0) = c_1x_1 + c_2x_2 + c_3x_3$  in the eigenvectors.
- 2. Multiply those eigenvectors by \_\_\_\_\_, \_\_\_\_,
- 3. Add up the solution  $u(t) = c_1 \_ x_1 + c_2 \_ x_2 + c_3 \_ x_3$ .

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- **3** (30 pts.) Suppose the vectors x, y give an orthonormal basis for  $\mathbf{R}^2$  and  $A = xy^{\mathrm{T}}$ .
  - (a) Compute the rank of A and the rank of  $A^2 = (xy^T)(xy^T)$ . Use this information to find the eigenvalues of A.
  - (b) Explain why this matrix B is **similar** to A (and write down what similar means):

$$B = \begin{bmatrix} & x^{\mathrm{T}} \\ & y^{\mathrm{T}} \end{bmatrix} A \begin{bmatrix} x & y \end{bmatrix}$$

(c) The eigenvalues of Q are  $\lambda_1 = e^{i\theta} = \cos\theta + i\sin\theta$  and  $\lambda_2 = e^{-i\theta} = \cos\theta - i\sin\theta$ :

Rotation matrix 
$$Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

Find the eigenvectors of Q. Are they perpendicular?

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