### 18.06 Problem Set 8

Due Wednesday, 23 April 2008 at 4 pm in 2-106.

Problem 1: Do problem 3 in section 6.5 (pg. 339) in the book.

Problem 2: Do problem 6 in section 6.5 (pg. 339).

Problem 3: For what numbers $c$ and $d$ are the matrices $A$ and $B$ positive definite? Test the 3 determinants:

$$
\begin{aligned}
& A=\left[\begin{array}{lll}
c & 2 & 3 \\
2 & c & 4 \\
3 & 4 & 1
\end{array}\right] \\
& B=\left[\begin{array}{lll}
1 & 2 & 1 \\
2 & d & 3 \\
1 & 3 & 1
\end{array}\right]
\end{aligned}
$$

Problem 4: Do problem 15 in section 6.5 (pg. 340).

Problem 5: Do problem 28 in section 6.5 (pg. 342).

Problem 6: a) Let $f_{1}(x, y)=\frac{1}{4} x^{4}+x^{2} y+y^{2}$. Find the second derivative matrix

$$
A_{1}=\left[\begin{array}{cc}
\partial^{2} f / \partial x^{2} & \partial^{2} f / \partial x \partial y \\
\partial^{2} f / \partial y \partial x & \partial^{2} f / \partial y^{2}
\end{array}\right]
$$

$A_{1}$ is not positive definite everywhere - find the conditions on $x$ and $y$ for it to be positive definite. (Interesting question: check what happens when both partial derivatives vanish, that is, when $\partial f / \partial x=\partial f / \partial y=0$. Is $f$ still positive definite? It turns out that $f_{1}$ does attain a minimal value, but not along isolated points. Find the points where it hits a global minimum. This part is not required.)
b) Let $f_{2}(x, y)=x^{3}+x y-x$. Find the second derivative matrix $A_{2}$. When is this matrix positive definite? (Interesting question: check what happens when both partial derivatives vanish, so when $\partial f / \partial x=\partial f / \partial y=0$. Show that you get a saddle point. This part is not required.)

Problem 7: Do problem 3 in section 8.1 (pg. 410).

Problem 8: Do problem 11 in section 8.1 (pg. 411). This problem requires Matlab.
Here, we are thinking of $u$ as a vector whose components represent a potential solution at the points $0,1 / 8,2 / 8, \ldots$ that satisfies the boundary conditions $u(0)=$ $u(1)=0$. So $u$ has 9 components, where the first and last components are 0 and the rest are variables that we are solving for.

In this case, discretizing the differential equation amounts to solving a matrix equation $M u=f$, where $M$ is a matrix found by combining the differential operators, and $f$ is the constant vector $[1,1,1, \ldots]$. The operator $d u / d x$ can be approximated by multiplying $u$ by the difference matrix

$$
A=\frac{1}{1 / 8}\left[\begin{array}{cccc}
1 & 0 & 0 & \ldots \\
-1 & 1 & 0 & \ldots \\
0 & -1 & 1 & \ldots \\
\vdots & \vdots & \ddots &
\end{array}\right]
$$

Here, $1 / 8$ represents the change $\Delta x$, and the matrix takes successive differences $u\left(x_{0}\right)-u\left(x_{0}-\Delta x\right)$, so the resulting vector has entries approximating the slopes of $u$. The matrix $A$ should have 9 columns (one for each entry of $u$ ) and 9 rows (one for each difference, plus an extra first row).

We can also define another difference matrix $A^{T}$; this represents $-d u / d x$ because now we are taking differences $u\left(x_{0}\right)-u\left(x_{0}+\Delta x\right)$. This will again be 9 by 9 . Finally, $-d^{2} u / d x^{2}$ can be approximated by multiplying by the second difference matrix

$$
A^{T} A=\frac{1}{1 / 64}\left[\begin{array}{ccccc}
2 & -1 & 0 & 0 & \ldots \\
-1 & 2 & -1 & 0 & \ldots \\
0 & -1 & 2 & -1 & \ldots \\
\vdots & \vdots & \vdots & \ddots &
\end{array}\right]
$$

So, the question asks us to solve the two systems $\left(A^{T} A+10 A\right) u=[1,1,1, \ldots]^{T}$ (using the forward difference) and $\left(A^{T} A-10 A^{T}\right) u=[1,1,1, \ldots]^{T}$ (using the backwards difference), subject to the conditions $u(0)=u(1)=0$. The easiest way to model the boundary conditions is simply to cut off the top and bottom entries of $u$, and then to cut off the first and last columns and rows of the matrix multiplying it. This will leave a vector $u$ with 7 components and a multiplier that is also 7 by 7 . Then we can use Matlab to solve $M u=[1,1,1, \ldots]^{T}$.

To plot points, first create a vector $x$ containing the $x$ coordinates. Then

```
plot(x,u,'+k')
```

will show a graph of your points marked by + symbols. To differentiate your two results, the command

```
plot(x,u,'xk')
```

will use x symbols instead.

