

MIT 18.06 Final Exam, Fall 2017  
Johnson

Your name: \_\_\_\_\_

Recitation: \_\_\_\_\_

problem	score
1	/15
2	/15
3	/15
4	/15
5	/15
6	/15
7	/10
total	/100

**Problem 1 (15 points):**

A matrix  $A = LU$  has the LU factors

$$L = \begin{pmatrix} 1 & & & \\ -2 & 1 & & \\ 0 & -2 & 1 & \\ -1 & -1 & -2 & 1 \end{pmatrix}, U = \begin{pmatrix} 1 & -1 & -2 & 0 \\ & 1 & 0 & -2 \\ & & 1 & 0 \\ & & & 1 \end{pmatrix}$$

- (a) If  $b = \begin{pmatrix} -1 \\ 2 \\ 2 \\ -4 \end{pmatrix}$ , what is  $x = A^{-1}b$ ?
- (b) Assuming you solved the previous part efficiently, roughly how much more arithmetic operations would be required for the same approach if the matrices were  $8 \times 8$  instead of  $4 \times 4$ ? It should be about \_\_\_\_\_ times more.
- (c) If you form a new  $4 \times 5$  matrix  $B = ( A \ b )$  by appending the vector  $b$  (from above) as an extra column after  $A$ , and perform the *same* elimination steps as were used to get the LU factors above, what upper-triangular matrix would you obtain? (Hint: if you did part (a) properly, this part can be done with *no arithmetic*.)

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**Problem 2 (15 points):**

You are given the recurrence relation

$$(2I + B^T B)x_{n+1} = (2I - B^T B)x_n$$

where  $B$  is a real  $5 \times 3$  matrix. We start with a vector  $x_0$  and compute  $x_1, x_2, \dots$

- (a)  $x_n = A^n x_0$  for some matrix  $A$  (independent of  $x_0$ ). What is  $A$ ?
- (b) If  $\lambda$  is an eigenvalue of  $B^T B$ , give an eigenvalue of  $A$ .
- (c) **Circle all possible** behaviors of  $x_n$  for large  $n$ , given the information above: **decaying** to zero, **oscillating** but not growing or decaying in length, going to a **nonzero constant** vector, or **growing** longer and longer. Explain your answers by giving some property (or properties) that must be true of the eigenvalues of  $A$ .
- (d) If  $x_1 = 0$  for a nonzero  $x_0$ , give one of the singular values ( $\sigma$ ) of  $B$ .

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### Problem 3 (15 points):

The distance between a point  $b$  and a plane in  $\mathbb{R}^3$  is defined as the *minimum* distance  $\|b - y\|$  between  $b$  and *any* point  $y$  in the plane.

- (a) Suppose the points  $y$  in the plane are of the form  $y = c + \alpha a_1 + \beta a_2$  for all real numbers  $\alpha$  and  $\beta$ , given vectors  $c, a_1, a_2 \in \mathbb{R}^3$  that define the plane ( $a_1$  and  $a_2$  are linearly independent). Under **what condition(s)** on  $c, a_1, a_2$  is the plane a **subspace** of  $\mathbb{R}^3$ ?
- (b) Write down a  $2 \times 2$  **system of equations**, in terms of the vectors  $a_1, a_2, c, b$  (or matrices defined from these vectors) whose solution gives the  $\begin{pmatrix} \alpha \\ \beta \end{pmatrix}$  for the *closest* point  $y$  in the plane to  $b$ .
- (c) For this closest point  $y$ ,  $b - y$  is in **what subspace** of the matrix  $A = (a_1 a_2)$ ? What is the **dimension** of this subspace?
- (d) For  $a_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ ,  $a_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ , **find a vector**  $d$  such that the distance between any point  $b$  and the plane is equal to  $|d^T(b - c)|$ . **What subspace** of  $A$  contains  $d$ ?

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**Problem 4 (15 points):**

You are given the following matrix:

$$A = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 2 & 1 & -3 & 4 \\ 1 & -2 & 1 & -4 \end{pmatrix}$$

- (a) Find the **complete solution**  $x$  (i.e. all solutions) to  $Ax = b$  for  $b = \begin{pmatrix} 3 \\ 9 \\ -4 \end{pmatrix}$ .
- (b)  $A^T y = d$  is solvable if and only if  $d^T z = 0$  for some  $z$ . **Give such a vector**  $z$ .



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**Problem 5 (15 points):**

QR factorization of the matrix  $A$  (e.g. via Gram-Schmidt) yields  $A = QR$ , where

$$Q = \begin{pmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{2} \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{2} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{2} \\ 0 & -\frac{1}{\sqrt{2}} & \frac{1}{2} \end{pmatrix}, R = \begin{pmatrix} 1 & 2 & 0 \\ & 1 & 2 \\ & & 2 \end{pmatrix}.$$

(a) Which columns of  $A$  were **orthogonal** to begin with, if any?

(b) What is the orthogonal **projection**  $p$  of the vector  $b = \begin{pmatrix} 4 \\ 0 \\ 0 \\ 0 \end{pmatrix}$  onto  $C(A)$ ?

(c) If we are minimizing  $\|Ax - b\|$  (i.e. solving the least-square problem) for

$b = \begin{pmatrix} 4 \\ 0 \\ 0 \\ 0 \end{pmatrix}$ , you should be able to *quickly get an upper-triangular*

**system** of equations  $U\hat{x} = c$  for the least-square solution  $\hat{x}$ . **What are the** upper-triangular matrix  $U$  and the right-hand-side vector  $c$ ?

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**Problem 6 (15 points):**

You are given the nonsymmetric, diagonalizable matrix

$$A = \begin{pmatrix} -1 & 1 & 3 \\ 1 & -3 & -2 \\ -1 & 0 & -3 \end{pmatrix}.$$

and we want to understand the solutions of the ODE

$$\frac{dx}{dt} = Ax$$

for some initial condition  $x(0)$ .

- (a) Show (by any test you want, e.g. the pivot test) that the matrix  $A + A^H =$   
 $\begin{pmatrix} -2 & 2 & 2 \\ 2 & -6 & -2 \\ 2 & -2 & -6 \end{pmatrix}$  is **negative definite**.
- (b) If  $Av = \lambda v$  is an eigensolution of  $A$  ( $v$  and  $\lambda$  may be complex), look at  $v^H (A + A^H) v$  and use the fact that  $A + A^H$  is negative definite to **show** that the **real part** of  $\lambda$  must be **negative**.
- (c) What can you conclude from the previous parts about the solutions  $x(t)$  as  $t \rightarrow \infty$ ?
- (d) If  $A + A^H$  is negative definite (so that  $A$ 's eigenvalues have negative real parts), but  $A$  is **defective**, does your answer to the previous part about  $x(\infty)$  **change? Why** or why not?

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**Problem 7 (10 points):**

The following parts can be **answered independently** (and refer to **different matrices**). Little or no calculation should be needed.

- (a) If  $C(B)$  is a subspace of  $N(A)$ , then either (**circle one**)  $AB$  or  $BA$  must be simply \_\_\_\_\_.
- (b) If  $A$  is a real-symmetric  $3 \times 3$  matrix with eigenvalues  $\lambda_1 = 1$ ,  $\lambda_2 = 2$ ,  $\lambda_3 = 3$  and corresponding real eigenvectors  $v_1, v_2, v_3$ , then an explicit equation for  $A^{-1}b$  in terms of sums/products involving these eigenvectors and  $b$ , with *no matrix inverses*, is:

\_\_\_\_\_.

- (c) If  $A$  is a  $3 \times 3$  non-singular real matrix with singular values  $\sigma_1, \sigma_2, \sigma_3$ , then give formulas in terms of  $\sigma_1, \sigma_2, \sigma_3$  for  $\det(A^T A) =$  \_\_\_\_\_ and  $|\det(A)| =$  \_\_\_\_\_.
- (d) If  $N(A)$  is spanned by the vector  $v \neq 0$ , then projection matrices onto *two* of the fundamental subspaces of  $A$  are:

\_\_\_\_\_ and \_\_\_\_\_  
(write down two matrices and indicate which subspaces they project onto).

- (e) If  $A$  is similar to the matrix  $\begin{pmatrix} 3 & 6 & 2 \\ & 17 & 3 \\ & & 4 \end{pmatrix}$ , then the eigenvalues of  $A$  are: \_\_\_\_\_.

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