Problem 18 Section 6.1

Since ${\cal A}$ has 2 distinct eigenvalues it can be diagonalized :

$$A = S^{-1} \begin{pmatrix} 4 & 0 \\ 0 & 5 \end{pmatrix} S$$

For $S_1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ $A_1 = \begin{pmatrix} 4 & 0 \\ 0 & 5 \end{pmatrix}$
 $S_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ $A_2 = \begin{pmatrix} 5 & 0 \\ 0 & 4 \end{pmatrix}$
 $S_3 = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$ $A_3 = S_3 \begin{pmatrix} 4 & 0 \\ 0 & 5 \end{pmatrix}$ $S_3^{-1} = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 5 \end{pmatrix} \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 4 & 1 \\ 0 & 5 \end{pmatrix}$

Problem 30 Section 6.1

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} a+b \\ c+d \end{pmatrix} = (a+b) \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \text{if} \quad a+b=c+d=\lambda_1$$

tr $A = a+d = \lambda_1 + \lambda_2 \implies \lambda_2 = a+d-(a+b) = d-b(=a-c)$
The eigenvector corresponding to λ_2 :
$$\begin{pmatrix} a-\lambda_2 & b \\ c & d-\lambda_2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
$$\begin{pmatrix} c & b \\ c & b \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \implies \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} b \\ -c \end{pmatrix}$$

Problem 7 Section 6.2

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \text{ has eigenvectors } \underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \text{ and } \underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

This means:

$$\begin{pmatrix} a - \lambda_1 & b \\ c & d - \lambda_1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ and } \begin{pmatrix} a - \lambda_2 & b \\ c & d - \lambda_2 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

From this $\begin{pmatrix} a + b - \lambda_1 \\ c + d - \lambda_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ and $\begin{pmatrix} a - b - \lambda_2 \\ c - d + \lambda_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
Or $\begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} \lambda_1 \\ \lambda_1 \\ \lambda_2 \\ \lambda_2 \end{pmatrix}$ The solution: $a = d = \frac{\lambda_1 + \lambda_2}{2}$
 $c = b = \frac{\lambda_1 - \lambda_2}{2}$

Thus the general form of the matrix is $\begin{pmatrix} a & b \\ b & a \end{pmatrix}$ with a, b any number.

Problem 11 Section 6.2

If A is 3×3 then

(a) true: det
$$A = 2 \cdot 2 \cdot 5 = 20 \neq 0$$

(b) false: $A = \begin{pmatrix} 2 & 1 \\ & 2 \\ & & 5 \end{pmatrix}$
(c) false: $A = \begin{pmatrix} 2 \\ & 2 \\ & & 5 \end{pmatrix}$

$$a = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \qquad P = \frac{a^{\mathrm{T}} a}{a a^{\mathrm{T}}} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$$

One can directly compute the eigenvalues by solving det $\begin{pmatrix} 1-\lambda & 1\\ 1 & 1-\lambda \end{pmatrix} = 0$

This gives $\lambda_1 = 0$ and $\lambda_2 = 1$, and the eigenvectors

for
$$\lambda_1 = 0$$
 $\frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $\underline{v}_1 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$
for $\lambda_2 = 1$ $\frac{1}{2} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $\underline{v}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$



$$\begin{split} & \frac{d\,\underline{u}(t)}{dt} = -P\;\underline{u}(t) \qquad \underline{u}(0) = \begin{pmatrix} 3\\1 \end{pmatrix} = 2\,\underline{v}_1 + 1\,\underline{v}_2 \\ & \text{We look for }\underline{u}(t) \text{ in the form } \qquad \underline{u}(t) = x(t)\underline{v}_1 + y(t)\underline{v}_2 \end{split}$$

 $-P \underline{u}(t) = -P(x(t) \underline{v}_1 + y(t) \underline{v}_2) = -x(t) \underline{v}_1 + 0$ $\frac{d \underline{u}(t)}{dt} = \frac{d x(t)}{dt} \underline{v}_1 + \frac{d y(t)}{dt} \underline{v}_2$ This means $\frac{d x(t)}{dt} = -x(t) \qquad x(0) = 2$ $\frac{d y(t)}{dt} = 0 \qquad y(0) = 1$ Solving the equations: $\begin{array}{l} x(t) &= & 2e^{-t} \\ y(t) &= & 1 \end{array}$

Thus
$$\underline{u}(t) = 2e^{-t} \underline{v}_1 + \underline{v}_2 = \begin{pmatrix} 2e^{-t} + 1\\ 2e^{-t} - 1 \end{pmatrix}$$

Problem 3 Section 6.6

• $A_1 = \begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix}$ $B_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

eigenvalues: 1 and 0

eigenvectors:
$$\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
 and $\underline{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
 $\underline{u}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\underline{u}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
 $\underline{u}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $\underline{u}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
 $\underline{u}_2 = \underline{v}_2$
Thus $M_1 = \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$
• $A_2 = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix}$
 $B_2 = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$

eigenvalues: 2 and 0

eigenvectors:
$$\underline{v}_1 = \begin{pmatrix} 1\\1 \end{pmatrix}$$
 $\underline{v}_2 = \begin{pmatrix} 1\\-1 \end{pmatrix}$ $\underline{u}_1 = \begin{pmatrix} 1\\-1 \end{pmatrix}$ $\underline{u}_2 = \begin{pmatrix} 1\\1 \end{pmatrix}$

$$M_2 = \begin{pmatrix} 0 & -2\\-2 & 0 \end{pmatrix}$$
 $\begin{pmatrix} 0 & -\frac{1}{2}\\-\frac{1}{2} & 0 \end{pmatrix} \begin{pmatrix} 1 & -1\\-1 & 1 \end{pmatrix} \begin{pmatrix} 0 & -2\\-2 & 0 \end{pmatrix} = \begin{pmatrix} 1 & -1\\-1 & 1 \end{pmatrix}$

$$A_3 = \begin{pmatrix} 1 & 2\\3 & 4 \end{pmatrix}$$
 $B_3 = \begin{pmatrix} 4 & 3\\2 & 1 \end{pmatrix}$

eigenvalues: 2 and 0

•

eigenvectors:
$$\underline{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$
 $\underline{v}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ $\underline{u}_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ $\underline{u}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$
 $M_3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$

Problem 18 Section 6.6

 $B\left(AB\right)B^{-1}=BA$

Problem 4 Section 8.3

Since the sum in each column is 1 we have: $A^{\mathrm{T}}\begin{pmatrix}1\\1\\1\\1\end{pmatrix} = \begin{pmatrix}1\\1\\1\\1\end{pmatrix}$

Problem 11 Section 8.3

The sum in each column is 1, thus

$$A = \begin{pmatrix} .7 & .1 & .2 \\ .1 & .6 & .3 \\ .2 & .3 & .5 \end{pmatrix}$$

A is symmetric thus $\begin{pmatrix} 1\\1\\1 \end{pmatrix}$ is an eigenvector of A corresponding to the eigenvalue 1. This means it is a steady state.