Due Thursday, 21 Oct.

1. Problem 5, section 4.3, p.226.

Solution: In matrix form, the unsolvable equations become  $A\hat{x} = b$  with A = [1; 1; 1; 1] and b = [0; 8; 8; 20]. So  $A^{T}A\hat{x} = A^{T}b$  is 4C = 36. Thus the best height C is given by C = 9 and the error vector  $e = b - A\hat{x}$  by e = [-9; -1; -1; 11]. The pictorial form of the horizontal line and the four errors is drawn on the right.



2. Problem 12, section 4.3, p.228.

#### Solution:

(a) Here  $a^{\mathrm{T}}a = m$  and  $a^{\mathrm{T}}b = b_1 + \dots + b_m$ . So  $a^{\mathrm{T}}a\hat{x} = a^{\mathrm{T}}b$  yields the mean:  $\hat{x} = (b_1 + \dots + b_m)/m$ .

(b) Here  $e = b - a\hat{x}$  is  $e = [b_1 - \hat{x}; \dots; b_m - \hat{x}]$ . So the <u>variance</u> is  $\boxed{||e||^2 = (b_1 - \hat{x})^2 + \dots + (b_m - \hat{x})^2}$ and the <u>standard deviation</u> is  $\boxed{||e|| = \sqrt{(b_1 - \hat{x})^2 + \dots + (b_m - \hat{x})^2}}$ .

(c) Here 
$$p = [3;3;3]$$
 and  $e = [-2;-1;3]$ . So  $p^{\perp}e = 3*(-2)+3*(-1)+3*3 = 0$   
and  $P = a(a^{\mathrm{T}}a)^{-1}a^{\mathrm{T}} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}$ .

### 3. Problem 2.5, section 4.3, p.229.

<u>Solution</u>: Geometrically, the condition is that the segment from the first point to the second has the same slope as the segment from the second point to the third; that is,

$$(b_2 - b_1)/(t_2 - t_1) = (b_3 - b_2)/(t_3 - t_2)$$

Algebraically, the condition is that  $(t_1, b_1)$  and  $(t_2, b_2)$  and  $(t_3, b_3)$  must satisfy some linear equation C + Dt = b. In other words, the vector  $[b_1; b_2; b_3]$  must be in column space of the matrix  $A = \begin{bmatrix} 1 & t_1 \\ 1 & t_2 \\ 1 & t_3 \end{bmatrix}$ . That space is the orthogonal complement of the left nullspace  $N(A^{T})$ . To find  $N(A^{T})$ , we row reduce  $A^{T}$  all the way to echelon form  $\operatorname{rref}(A^{T})$ :

$$\begin{aligned} A^{\mathrm{T}} &= \begin{bmatrix} 1 & 1 & 1 \\ t_1 & t_2 & t_3 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & t_2 - t_1 & t_3 - t_1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 1 & (t_3 - t_1)/(t_2 - t_1) \end{bmatrix} \\ &\longrightarrow \begin{bmatrix} 1 & 0 & (t_2 - t_3)/(t_2 - t_1) \\ 0 & 1 & (t_3 - t_1)/(t_2 - t_1) \end{bmatrix} = \mathrm{rref}(A^{\mathrm{T}}). \end{aligned}$$

Hence  $N(A^{\mathrm{T}})$  consists of all multiples of the special solution  $y = [-(t_2-t_3)/(t_2-t_1), -(t_3-t_1)/(t_2-t_1), 1]$ . So the condition becomes  $y^{\mathrm{T}}[b_1; b_2; b_3] = 0$ , or

$$-b_1(t_2-t_3)/(t_2-t_1), -b_2(t_3-t_1)/(t_2-t_1)+b_3=0.$$

Finally, this equation is equivalent to the one displayed above.

### 4. Problem 1, section 4.4, p.239.

<u>Solution</u>: The pairs are in (a) only independent, in (b) both independent and orthogonal, and in (c) all three. To produce orthonormal vectors, change the second vector in (a) to [0;1] and in (b) to  $[.4;-.3]/\sqrt{.16+.09} = [.8;-.6]$ .

#### 5. Problem 4, section 4.4, p.239.

Solution: Examples are the following: (a) 
$$Q = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$
 with  $Q Q^{\mathrm{T}} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ ;  
(b)  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$  and  $\begin{bmatrix} 1 \\ 0 \end{bmatrix}$ ; and (c)  $q_2 = (1, -1, 0)/\sqrt{2}$  and  $q_3 = (1, 1, -2)/\sqrt{6}$ .

## 6. Problem 18, section 4.4, p.241.

Solution: The Gram-Schmidt process yields the following:

$$A = a = \boxed{(1, -1, 0, 0)};$$
  

$$B = b - p_A = (0, 1, -1, 0) - (1, -1, 0, 0) * (-1)/2 = \boxed{(1/2, 1/2, -1, 0)};$$
  

$$C = c - p_A - p_B = (0, 0, 1, -1) - (1, -1, 0, 0) * (0)/2 - (1/2, 1/2, -1, 0) * (-1)/(1/4 + 1/4 + 1 + 0))$$
  

$$= \boxed{(1/3, 1/3, 1/3, -1)}.$$

# 7. Problem 20, section 4.4, p.241.

Solution: (a) True, an example is 
$$Q = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} / \sqrt{2}$$
 with  $Q^{-1} = Q^{T} = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} / \sqrt{2}$ .  
(b) True as  $Q = \begin{bmatrix} q_{1} & q_{2} \end{bmatrix}$  implies  $||Q x||^{2} = (x_{1} q_{1}^{T} + x_{2} q_{2}^{T}) * (q_{1} x_{1} + q_{2} x_{2}) = x_{1}^{2} + x_{2}^{2}$   
since  $q_{1}^{T} q_{1} = 1$ ,  $q_{1}^{T} q_{2} = 0$  and  $q_{2}^{T} q_{2} = 1$ . An example is  $Q = \begin{bmatrix} 1/\sqrt{3} & 1/\sqrt{2} \\ 1/\sqrt{3} & -1/\sqrt{2} \\ 1/\sqrt{3} & 0 \end{bmatrix}$   
and  $x = \begin{bmatrix} \sqrt{3} \\ \sqrt{2} \end{bmatrix}$ . Here  $Q x = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$ . So  $||Q x||^{2} = 4 + 1 = 5$ .  
And  $||x||^{2} = 3 + 2 = 5$ .

## 8. Problem 2, section 8.5, p.451.

Solution: Three integration show that the polynomial 1, x,  $x^2 - 1/3$  are orthogonal on the interval [-1, 1]:

$$\int_{-1}^{1} (1)(x) dx = [x^2/2]_{-1}^{1} = 0;$$
  
$$\int_{-1}^{1} (1)(x^2 - 1/3) dx = [x^3/3 - x/3]_{-1}^{1} = 2(1/3 - 1/3) = 0;$$
  
$$\int_{-1}^{1} (x)(x^2 - 1/3) dx = [x^4/4 - x^2/6]_{-1}^{1} = 0.$$

Clearly, any polynomial of degree 2 can be written as a linear combination of 1, x,  $x^2 - 1/3$ . By inspection,  $2x^2 = 2(x^2 - 1/3) + 0(x) = (2/3)(1)$ . Those coefficients 2, 0, 2/3 can also be found by integrating  $f(x) = 2x^2$  times the three basis functions and dividing by their "length" squared.

## 9. Problem 4, section 8.5, p.451.

Solution: On [-1, 1], the integrals of any odd function vanishes. So for any c,

$$\int_{-1}^{1} (1)(x^3 - cx)dx = 0 \quad \text{and} \quad \int_{-1}^{1} (1)(x^2 - 1/3)(x^3 - cx)dx = 0.$$

Choose c so that the remaining integral vanishes:

$$\int_{-1}^{1} (x)(x^3 - cx)dx = [x^5/5 - cx^3/3]_{-1}^{1} = 2(1/5 - c/3) = 0.$$
  
hus  $c = 3/5$ .

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### 10. Problem 6, section 8.5, p.451.

<u>Solution</u>: Equations (6) and (8) on p.449 yield  $2\pi = \pi (4/\pi)^2 (1/1^2 + 1/3^2 + 1/5^2 + \cdots) \quad \text{or}$   $\boxed{\pi^2 = 8(1/1^2 + 1/3^2 + 1/5^2 + \cdots)}.$ 

11. Find the best linear approximation to  $y = x^2$  on [-1, 1].

<u>Solution</u>: In problem 2, section 8.5, it was shown that  $1, x, x^2 - 1/3$  are orthogonal. By inspection,  $x^2 = 1(x^2 - 1/3) + 0(x) + (1/3)(1)$ . Hence the orthogonal projection of  $y = x^2$  into the span of 1 and x is y = 1/3, which is therefore the best linear approximation.