# 18.06 Problem Set 5 Due Wednesday, Oct. 18, 2006 at **4:00 p.m.** in 2-106

#### Problem 1 Wednesday 10/11

For each of these, find a matrix satisfying the conditions given or explain why none can exist.

(a) Column space contains 
$$\begin{bmatrix} -1\\1\\1\\1 \end{bmatrix}$$
 and  $\begin{bmatrix} 1\\-2\\1\\1 \end{bmatrix}$ , and nullspace contains  $\begin{bmatrix} 3\\2\\1\\1 \end{bmatrix}$   
(b) Row space contains  $\begin{bmatrix} -1\\1\\1\\1 \end{bmatrix}$  and  $\begin{bmatrix} 1\\-2\\1\\1 \end{bmatrix}$ , and nullspace contains  $\begin{bmatrix} 3\\2\\1\\1 \end{bmatrix}$   
(c)  $Ax = \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$  is solvable;  $A^{\mathsf{T}} \begin{bmatrix} 3\\2\\1 \end{bmatrix}$  is zero.

(d) A nonzero matrix where every row is perpendicular to every column

(e) Rows sum to a row of zeros, and columns sum to  $\begin{bmatrix} 2\\3\\-1 \end{bmatrix}$ 

## Problem 2 Wednesday 10/11

Do Problem #12 from section 4.1 in your book.

#### Problem 3 Wednesday 10/11

Do Problem #26 from section 4.1 in your book.

#### Problem 4 Friday 10/13

Do Problem #2 from section 4.2 in your book. What is the permutation matrix P? What is the error e = b - p?

#### Problem 5 Friday 10/13

Do Problem #13 from section 4.2 in your book. Do this two different ways:

(a) geometrically, tell what subspace we're projecting b orthogonally onto

(b) algebraically, calculate  $P = A(A^{\mathsf{T}}A)^{-1}A^{\mathsf{T}}$ 

#### Problem 6 Friday 10/13

A subspace **S** has basis 
$$\left\{ a = \begin{bmatrix} 2 \\ -1 \\ 0 \\ 1 \end{bmatrix}, b = \begin{bmatrix} 5 \\ 0 \\ -1 \\ 2 \end{bmatrix}, c = \begin{bmatrix} 0 \\ 5 \\ 4 \\ -1 \end{bmatrix} \right\}.$$

(a) What are the dot products  $a^{\dagger}b$ ,  $a^{\dagger}c$ ,  $b^{\dagger}c$ ? Are the basis vectors orthogonal?

Now let's compute a new basis  $\left\{\hat{a}, \hat{b}, \hat{c}\right\}$  for the same subspace. Start by letting  $\hat{a} = a$ .

(b) Compute the projection Pb of b onto the line described by a. What is the error (b - Pb)? Call this error vector  $\hat{b}$ .

(c) Compute the projection  $P_1c$  of c onto the plane described by a and b. What is the error  $(c - P_1c)$ ? Call this error vector  $\hat{c}$ . Does  $\hat{c}$  change if we project onto the plane with basis  $\hat{a}$  and  $\hat{b}$  instead? Why or why not?

(d) What are the dot products  $\hat{a}^{\mathsf{T}}\hat{b}$ ,  $\hat{a}^{\mathsf{T}}\hat{c}$ ,  $\hat{b}^{\mathsf{T}}\hat{c}$ ? Are the new basis vectors orthogonal? (This process for finding an orthogonal basis is called the "Gram-Schmidt Process" — the full version also scales each vector to "normalize" it to unit length.)

(f) Explain how you know  $\{\hat{a}, \hat{b}, \hat{c}\}$  is a basis for **S**. (Don't forget to show it both spans the subspace, and is linearly independent!)

## Problem 7 Monday 10/16

Do Problem #17 from section 4.3 in your book.

### Problem 8 Monday 10/16

Do Problem #27 from section 4.3 in your book.