## 18.06 Problem Set 10 Due Wednesday, Nov. 29, 2006 at **4:00 p.m.** in 2-106

Problem 1 Monday 11/20

Do Problem #7 from section 8.1 in your book.

Problem 2 Wednesday, 11/22Do Problem #3 from section 6.6 in your book.

Problem 3 Wednesday, 11/22
Do Problem #11 from section 6.6 in your book.

Problem 4 Wednesday, 11/22

Do Problem #12 from section 6.6 in your book.

Problem 5 Monday, 11/27

Do Problem #7 from section 6.7 in your book.

Problem 6 Monday, 11/27

Do Problem #12 from section 6.7 in your book.

Problem 7 Monday, 11/27

Do Problem #15 from section 6.7 in your book.

## Problem 8 for Wednesday, 11/29

One way of thinking about matrix multiplication is as a *linear transformation* — just as y = ax is a linear function transforming an input x to an output y, we can think of y = Ax as a "linear" function, transforming our input vector x (in  $\mathbb{R}^n$ ) to output vector y (in  $\mathbb{R}^m$ ). Formally, a function y = T(x) is "linear" if

- T(u+v) = T(u) + T(v) (we can break up sums)
- T(cv) = cT(v) (we can pull out constant factors)

So, for example, f(x) = 3x is linear, because  $3(x_1 + x_2) = 3x_1 + 3x_2$  and  $3(cx) = c \cdot 3x$ ; but  $f(x) = \sin(x)$  isn't linear, because  $\sin(a + b) \neq \sin(a) + \sin(b)$ . Which of these are linear? Why or why not?

1.  $y = x^2$  (input and output are in R) 2.  $g(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}) = x_1 + 3x_2$  (input in  $R^2$ , output in R)

- 3. f(x) = 3x + 1 (careful!)
- 4.  $T(x) = \begin{bmatrix} 1 & 2 \\ -1 & 2 \end{bmatrix} x$  (input and output are in  $R^2$ )
- 5.  $L(f) = \int_0^1 f(t) dt$  (input is in a function space, output is in R)
- 6.  $M(f) = \frac{d^2 f}{dt^2}$  (input and output are both functions)

## Problem 9 for Wednesday, 11/29

If we pick a basis for the input and the output, we can write a linear transformation as a matrix. If  $T(u) = \begin{bmatrix} 3 \\ -2 \\ -5 \end{bmatrix}$  and  $T(v) = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ , then what is T(au + bv)? Now write down a matrix A for which  $A \begin{bmatrix} a \\ b \end{bmatrix} = T(au + bv)$ .