## Your PRINTED name is: <u>SOLUTIONS</u>

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1 (4+7=11 pts.) Suppose A is 3 by 4, and Ax = 0 has exactly 2 special solutions:

$$x_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix} \quad \text{and} \quad x_2 = \begin{bmatrix} -2 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

- (a) Remembering that A is 3 by 4, find its row reduced echelon form R.
- (b) Find the dimensions of all four fundamental subspaces C(A), N(A),  $C(A^{\rm T})$ ,  $N(A^{\rm T})$ .

You have enough information to find bases for one or more of these subspaces—find those bases.

(a) Each special solution tells us the solution to Rx = 0 when we set one free variable = 1 and the others = 0. Here, the third and fourth variables must be the two free variables,

and the other two are the pivots: 
$$R = \begin{bmatrix} 1 & 0 & * & * \\ 0 & 1 & * & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Now multiply out 
$$Rx_1 = 0$$
 and  $Rx_2 = 0$  to find the \*'s:  $R = \begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ 

(The \*'s are just the negatives of the special solutions' pivot entries.)

(b) We know the nullspace N(A) has n-r=4-2=2 dimensions: the special solutions  $x_1, x_2$  form a basis.

The row space  $C(A^{\mathrm{T}})$  has r=2 dimensions. It's orthogonal to N(A), so just pick two linearly-independent vectors orthogonal to  $x_1$  and  $x_2$  to form a basis: for example,

$$x_3 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 2 \end{bmatrix}, x_4 = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 1 \end{bmatrix}.$$

(Or:  $C(A^{T}) = C(R^{T})$  is just the row space of R, so the first two rows are a basis. Same thing!)

The column space C(A) has r=2 dimensions (same as  $C(A^T)$ ). We can't write down a basis because we don't know what A is, but we can say that the first two columns of A are a basis.

The left nullspace  $N(A^{T})$  has m-r=1 dimension; it's orthogonal to C(A), so any vector orthogonal to the first two columns of A (whatever they are) will be a basis.

3

2 (6+3+2=11 pts.) (a) Find the inverse of a 3 by 3 upper triangular matrix U, with nonzero entries a, b, c, d, e, f. You could use cofactors and the formula for the inverse. Or possibly Gauss-Jordan elimination.

Find the inverse of 
$$U = \begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix}$$
.

- (b) Suppose the columns of U are eigenvectors of a matrix A. Show that A is also upper triangular.
- (c) Explain why this U cannot be the same matrix as the first factor in the Singular Value Decomposition  $A = U\Sigma V^{\mathrm{T}}$ .

(a) By elimination: (We keep track of the elimination matrix E on one side, and the product EU on the other. When EU = I, then  $E = U^{-1}$ .)

$$\begin{bmatrix} a & b & c & 1 & 0 & 0 \\ 0 & d & e & 0 & 1 & 0 \\ 0 & 0 & f & 0 & 0 & 1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & b/a & c/a & 1/a & 0 & 0 \\ 0 & 1 & e/d & 0 & 1/d & 0 \\ 0 & 0 & 1 & 0 & 0 & 1/f \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 0 & 0 & 1/a & -b/ad & (be - cd)/adf \\ 0 & 1 & 0 & 0 & 1/d & -e/df \\ 0 & 0 & 1 & 0 & 0 & 1/f \end{bmatrix} = \begin{bmatrix} I & U^{-1} \end{bmatrix}$$

By cofactors: (Take the minor, then "checkerboard" the signs to get the cofactor matrix, then transpose and divide by det(U) = adf.)

$$\begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix} \leadsto \begin{bmatrix} df & 0 & 0 \\ bf & af & 0 \\ be - cd & ae & ad \end{bmatrix} \leadsto \begin{bmatrix} df & 0 & 0 \\ -bf & af & 0 \\ be - cd & -ae & ad \end{bmatrix} \leadsto \begin{bmatrix} df & -bf & be - cd \\ 0 & af & -ae \\ 0 & 0 & ad \end{bmatrix} \leadsto \begin{bmatrix} 1/a & -b/ad & (be - cd)/adf \\ 0 & 1/d & -e/df \\ 0 & 0 & 1/f \end{bmatrix} = U^{-1}$$

- (b) We have a complete set of eigenvectors for A, so we can diagonalize:  $A = U\Lambda U^{-1}$ . We know U is upper-triangular, and so is the diagonal matrix  $\Lambda$ , and we've just shown that  $U^{-1}$  is upper-triangular too. So their product A is also upper-triangular.
- (c) The columns aren't orthogonal! (For example, the product  $u_1^T u_2$  of the first two columns is  $ab + 0d + 0 \cdot 0 = ab$ , which is nonzero because we're assuming all the entries are nonzero.)

3 (3+3+5=11 pts.) (a) A and B are any matrices with the same number of rows.

What can you say (and explain why it is true) about the comparison of

rank of 
$$A$$
 rank of the block matrix  $\begin{bmatrix} A & B \end{bmatrix}$ 

- (b) Suppose  $B = A^2$ . How do those ranks compare? Explain your reasoning.
- (c) If A is m by n of rank r, what are the dimensions of these nullspaces?

Null  
space of 
$$A$$
 Null  
space of  $\begin{bmatrix} A & A \end{bmatrix}$ 

Solution.

- (a) All you can say is that rank  $A \leq \text{rank } [A B]$ . (A can have any number r of pivot columns, and these will all be pivot columns for [A B]; but there could be more pivot columns among the columns of B.)
- (b) Now rank  $A = \text{rank } [A \ A^2]$ . (Every column of  $A^2$  is a linear combination of columns of A. For instance, if we call A's first column  $a_1$ , then  $Aa_1$  is the first column of  $A^2$ . So there are no new pivot columns in the  $A^2$  part of  $[A \ A^2]$ .)
- (c) The nullspace N(A) has dimension n-r, as always. Since  $[A\ A]$  only has r pivot columns the n columns we added are all duplicates  $[A\ A]$  is an m-by-2n matrix of rank r, and its nullspace  $N([A\ A])$  has dimension 2n-r.

- 4 (3+4+5=12 pts.) Suppose A is a 5 by 3 matrix and Ax is never zero (except when x is the zero vector).
  - (a) What can you say about the columns of A?
  - (b) Show that  $A^{T}Ax$  is also never zero (except when x=0) by explaining this key step:

If  $A^{T}Ax = 0$  then obviously  $x^{T}A^{T}Ax = 0$  and then (WHY?) Ax = 0.

(c) We now know that  $A^{T}A$  is invertible. Explain why  $B = (A^{T}A)^{-1}A^{T}$  is a one-sided inverse of A (which side of A?). B is NOT a 2-sided inverse of A (explain why not).

## Solution.

- (a) N(A) = 0 so A has full column rank r = n = 3: the columns are linearly independent.
- (b)  $x^{\mathrm{T}}A^{\mathrm{T}}Ax = (Ax)^{\mathrm{T}}Ax$  is the squared length of Ax. The only way it can be zero is if Ax has zero length (meaning Ax = 0).
- (c) B is a left inverse of A, since  $BA = (A^{T}A)^{-1}A^{T}A = I$  is the (3-by-3) identity matrix. B is not a right inverse of A, because AB is a 5-by-5 matrix but can only have rank 3. (In fact,  $BA = A(A^{T}A)^{-1}A^{T}$  is the projection onto the (3-dimensional) column space of A.)

5 (5+5=10 pts.) If A is 3 by 3 symmetric positive definite, then  $Aq_i = \lambda_i q_i$  with positive eigenvalues and orthonormal eigenvectors  $q_i$ .

Suppose  $x = c_1 q_1 + c_2 q_2 + c_3 q_3$ .

- (a) Compute  $x^{T}x$  and also  $x^{T}Ax$  in terms of the c's and  $\lambda$ 's.
- (b) Looking at the ratio of  $x^{T}Ax$  in part (a) divided by  $x^{T}x$  in part (a), what c's would make that ratio as large as possible? You can assume  $\lambda_{1} < \lambda_{2} < \ldots < \lambda_{n}$ . Conclusion: the ratio  $x^{T}Ax/x^{T}x$  is a maximum when x is \_\_\_\_\_.

Solution.

(a)

$$x^{\mathrm{T}}x = (c_1q_1^{\mathrm{T}} + c_2q_2^{\mathrm{T}} + c_3q_3^{\mathrm{T}})(c_1q_1 + c_2q_2 + c_3q_3)$$

$$= c_1^2q_1^{\mathrm{T}}q_1 + c_1c_2q_1^{\mathrm{T}}q_2 + \dots + c_3c_2q_3^{\mathrm{T}}q_2 + c_3^2q_3^{\mathrm{T}}q_3$$

$$= c_1^2 + c_2^2 + c_3^2.$$

$$x^{\mathrm{T}}Ax = (c_{1}q_{1}^{\mathrm{T}} + c_{2}q_{2}^{\mathrm{T}} + c_{3}q_{3}^{\mathrm{T}})(c_{1}Aq_{1} + c_{2}Aq_{2} + c_{3}Aq_{3})$$

$$= (c_{1}q_{1}^{\mathrm{T}} + c_{2}q_{2}^{\mathrm{T}} + c_{3}q_{3}^{\mathrm{T}})(c_{1}\lambda_{1}q_{1} + c_{2}\lambda_{2}q_{2} + c_{3}\lambda_{3}q_{3})$$

$$= c_{1}^{2}\lambda_{1}q_{1}^{\mathrm{T}}q_{1} + c_{1}c_{2}\lambda_{2}q_{1}^{\mathrm{T}}q_{2} + \dots + c_{3}c_{2}\lambda_{2}q_{3}^{\mathrm{T}}q_{2} + c_{3}^{2}\lambda_{3}q_{3}^{\mathrm{T}}q_{3}$$

$$= c_{1}^{2}\lambda_{1} + c_{2}^{2}\lambda_{2} + c_{3}^{2}\lambda_{3}.$$

(b) We maximize  $(c_1^2\lambda_1 + c_2^2\lambda_2 + c_3^2\lambda_3)/(c_1^2 + c_2^2 + c_3^2)$  when  $c_1 = c_2 = 0$ , so  $x = c_3q_3$  is a multiple of the eigenvector  $q_3$  with the largest eigenvalue  $\lambda_3$ .

(Also notice that the maximum value of this "Rayleigh quotient"  $x^{T}Ax/x^{T}x$  is the largest eigenvalue itself. This is another way of finding eigenvectors: maximize  $x^{T}Ax/x^{T}x$  numerically.)

- 6 (4+4+4=12 pts.) (a) Find a linear combination w of the linearly independent vectors v and u that is perpendicular to u.
  - (b) For the 2-column matrix  $A = \begin{bmatrix} u & v \end{bmatrix}$ , find Q (orthonormal columns) and R (2 by 2 upper triangular) so that A = QR.
  - (c) In terms of Q only, using A = QR, find the projection matrix P onto the plane spanned by u and v.

(a) You could just write down w = 0u + 0v = 0 — that's perpendicular to everything! But a more useful choice is to subtract off just enough u so that w = v - cu is perpendicular to u. That means  $0 = w^{\mathrm{T}}u = v^{\mathrm{T}}u - cu^{\mathrm{T}}u$ , so  $c = (v^{\mathrm{T}}u)/(u^{\mathrm{T}}u)$  and

$$w = v - (\frac{v^{\mathrm{T}}u}{u^{\mathrm{T}}u})u.$$

- (b) We already know u and w are orthogonal; just normalize them! Take  $q_1 = u/|u|$  and  $q_2 = w/|w|$ . Then solve for the columns  $r_1$ ,  $r_2$  of R:  $Qr_1 = u$  so  $r_1 = \begin{bmatrix} |u| \\ 0 \end{bmatrix}$ , and  $Qr_2 = v$  so  $r_2 = \begin{bmatrix} c|u| \\ |w| \end{bmatrix}$ . (Where  $c = (v^Tu)/(u^Tu)$  as before.)

  Then  $Q = [q_1 \ q_2]$  and  $R = [r_1 \ r_2]$ .
- (c)  $P = A(A^{T}A)^{-1}A^{T} = (QR)(R^{T}Q^{T}QR)^{-1}(R^{T}Q^{T}) = (QR)(R^{T}Q^{T}) = QQ^{T}$ .

7 (4+3+4=11 pts.) (a) Find the eigenvalues of

$$C = \begin{bmatrix} 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad \text{and} \quad C^2 = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}.$$

- (b) Those are both permutation matrices. What are their inverses  $C^{-1}$  and  $(C^2)^{-1}$ ?
- (c) Find the determinants of C and C + I and C + 2I.

(a) Take the determinant of  $C - \lambda I$  (I expanded by cofactors):  $\lambda^4 - 1 = 0$ . The roots of this "characteristic equation" are the eigenvalues: +1, -1, i, -i.

The eigenvalues of  $C^2$  are just  $\lambda^2 = \pm 1$  (two of each).

(Here's a "guessing" approach. Since  $C^4 = I$ , all the eigenvalues  $\lambda^4$  of  $C^4$  are 1: so  $\lambda = 1, -1, i, -i$  are the only possibilities. Just check to see which ones work. Then the eigenvalues of  $C^2$  must be  $\pm 1$ .)

(b) For any permutation matrix,  $C^{-1} = C^{T}$ : so

$$C^{-1} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

and  $(C^2)^{-1} = C^2$  is itself.

(c) The determinant of C is the product of its eigenvalues: 1(-1)i(-i) = -1.

Add 1 to every eigenvalue to get the eigenvalues of C+I (if  $C=S\Lambda S^{-1}$ , then  $C+I=S(\Lambda+I)S^{-1}$ ):  $2(0)(1+i)(1-i)=\underline{0}$ .

(Or let  $\lambda = -1$  in the characteristic equation  $\det(C - \lambda I)$ .)

Add 2 to get the eigenvalues of C + 2I (or let  $\lambda = -2$ ):  $3(1)(2+i)(2-i) = \underline{15}$ .

8 (4+3+4=11 pts.) Suppose a rectangular matrix A has independent columns.

- (a) How do you find the best least squares solution  $\hat{x}$  to Ax = b? By taking those steps, give me a formula (letters not numbers) for  $\hat{x}$  and also for  $p = A\hat{x}$ .
- (b) The projection p is in which fundamental subspace associated with A? The error vector e = b - p is in which fundamental subspace?
- (c) Find by any method the projection matrix P onto the column space of A:

$$A = \begin{bmatrix} 1 & 0 \\ 3 & 0 \\ 0 & -1 \\ 0 & -3 \end{bmatrix}.$$

Solution.

(a)

$$Ax = b$$
 Least-squares "solution":  $A^{T}A\hat{x} = A^{T}b$  
$$A^{T}A \text{ is invertible:} \quad \hat{x} = (A^{T}A)^{-1}A^{T}b$$
 and  $p = A\hat{x}$  is:  $A\hat{x} = A(A^{T}A)^{-1}A^{T}b$ 

- (b)  $p = A\hat{x}$  is a linear combination of columns of A, so it's in the column space C(A). The error e = b p is orthogonal to this space, so it's in the left nullspace  $N(A^{T})$ .
- (c) I used  $P = A(A^{T}A)^{-1}A^{T}$ . Since  $A^{T}A = \begin{bmatrix} 10 & 0 \\ 0 & 10 \end{bmatrix}$ , its inverse is  $\begin{bmatrix} 1/10 & 0 \\ 0 & 1/10 \end{bmatrix} = \frac{1}{10}I$ , and

$$P = \frac{1}{10} \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 9 & 0 & 0 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 3 & 9 \end{bmatrix}$$

9 (3+4+4=11 pts.) This question is about the matrices with 3's on the main diagonal, 2's on the diagonal above, 1's on the diagonal below.

$$A_{1} = \begin{bmatrix} 3 \end{bmatrix} \quad A_{2} = \begin{bmatrix} 3 & 2 \\ 1 & 3 \end{bmatrix} \quad A_{3} = \begin{bmatrix} 3 & 2 & 0 \\ 1 & 3 & 2 \\ 0 & 1 & 3 \end{bmatrix} \quad A_{n} = \begin{bmatrix} 3 & 2 & 0 & 0 \\ 1 & 3 & 2 & 0 \\ 0 & 1 & 3 & \cdot \\ 0 & 0 & \cdot & \cdot \end{bmatrix}$$

- (a) What are the determinants of  $A_2$  and  $A_3$ ?
- (b) The determinant of  $A_n$  is  $D_n$ . Use cofactors of row 1 and column 1 to find the numbers a and b in the recursive formula for  $D_n$ :

$$(*) D_n = a D_{n-1} + b D_{n-2}.$$

(c) This equation (\*) is the same as

$$\begin{bmatrix} D_n \\ D_{n-1} \end{bmatrix} = \begin{bmatrix} a & b \\ 1 & 0 \end{bmatrix} \begin{bmatrix} D_{n-1} \\ D_{n-2} \end{bmatrix}.$$

>From the eigenvalues of that matrix, how fast do the determinants  $D_n$  grow? (If you didn't find a and b, say how you would answer part (c) for any a and b) For 1 point, find  $D_5$ .

- (a)  $\det(A_2) = 3 \cdot 3 1 \cdot 2 = 7$  and  $\det(A_3) = 3 \det(A_2) 2 \cdot 1 \cdot 3 = 15$ .
- (b)  $D_n = 3D_{n-1} + (-2)D_{n-2}$ . (Show your work.)
- (c) The trace of that matrix A is a=3, and the determinant is -b=2. So the characteristic equation of A is  $\lambda^2 a\lambda b = 0$ , which has roots (the eigenvalues of A)

$$\lambda_{\pm} = \frac{a \pm \sqrt{a^2 - 4(-b)}}{2} = \frac{3 \pm 1}{2} = 1 \text{ or } 2.$$

 $D_n$  grows at the same rate as the largest eigenvalue of  $A^n$ ,  $\lambda_+^n = 2^n$ .

The final point:  $D_5 = 3D_4 + 2D_3 = 3(3D_3 + 2D_2) + 2D_3 = 11D_3 + 6D_2 = 207$ .